Department of Electrical Engineering University of Arkansas



ELEG4623/5663 Communication Theory Ch. 1 Signals and Spectra

Dr. Jingxian Wu wuj@uark.edu

OUTLINE

- Deterministic signals (Ch. 1.2, 1.3, 1.6 Appendix A)
- Random Signals
- Signal transmission through linear system, bandwidth



DETERMINISTIC: SIGNAL CLASSIFICATION

• Deterministic v.s. Random

- Deterministic signal: there is no uncertainty.w.r.t. signal value at any time.
 - E.g. $x(t) = 5 \exp(-2t) \cos(5t)$
- Random signal: there is some degree of uncertainty before the signal occurs.
 - E.g. noise
- Periodic v.s. Nonperiodic
 - A signal is called periodic in time if there exists a constant $T_0 > 0$ such that $x(t) = x(t+T_0)$
 - The smallest $T_0 > 0$ satisfying the above equation is called fundamental period.
 - E.g. find the fundamental period of $x(t) = \exp(-j\omega t)$
- Continuous-time v.s. Discrete-time signal
 - Continuous-time signal: the signal is defined over continuous-time. x(t)
 - Discrete-time signal: a signal that exists only at discrete-time values. $x(kT_s)$, x(k)
 - Discrete-time signals are undefined at $t \neq kT_s$



- Energy signal v.s. Power signal
 - Instantaneous power of a signal $p(t) = x^2(t)$
 - Energy of a signal dissipated during interval $\left(-\frac{T}{2}, \frac{T}{2}\right)$

 $E^{T} = \int_{-T/2}^{T/2} x^{2}(t) dt \qquad \left(-\frac{T}{2}, \frac{T}{2}\right)$ - Average power dissipated during interval $\left(-\frac{T}{2}, \frac{T}{2}\right)$

$$P^{T} = \frac{E^{T}}{T} = \frac{1}{T} \int_{-T/2}^{T/2} x^{2}(t) dt$$

– Total Energy of signal:

$$E = \lim_{T \to \infty} \int_{-T/2}^{T/2} x^2(t) dt = \int_{-\infty}^{\infty} x^2(t) dt$$

- Energy signal: $0 < E < \infty$
- Average power of signal:

$$P = \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt$$

- Average power of periodic sign $P = \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} x^2(t) dt = \frac{1}{T_0} \int_{0}^{T_0} x^2(t) dt$
- Power signal: $0 < P < \infty$



• Example:

 $x(t) = A\cos(\omega_0 t + \theta_0)$

- Find the fundamental period.
- Find the average power.



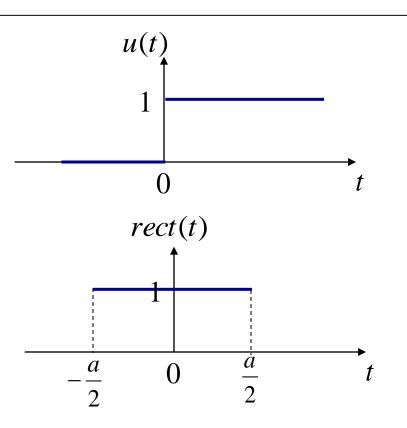
• Unit step function

$$u(t) = \begin{cases} 1, & t \ge 0\\ 0, & t < 0 \end{cases}$$

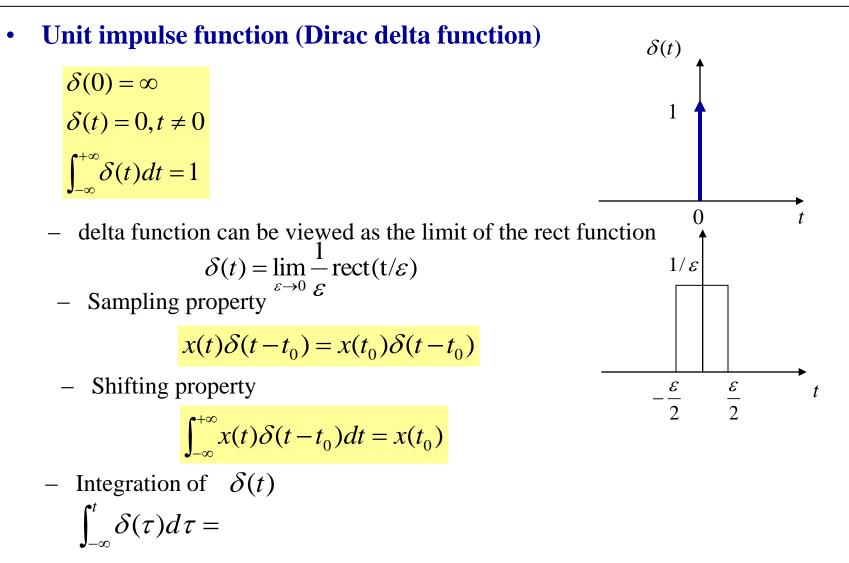
• Rectangular function

$$\operatorname{rect}\left(\frac{t}{a}\right) = \begin{cases} 1 & -\frac{a}{2} \le t \le \frac{a}{2} \\ 0 & o.w. \end{cases}$$

- rect(t) can be represented by using u(t):





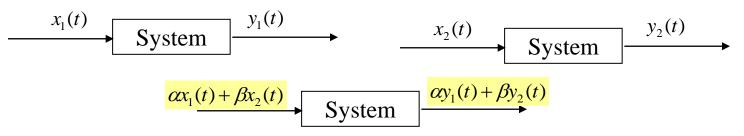




DETERMINISTIC: SYSTEM

• Linear system

- A system is linear if the superposition principal is satisfied.



- Time-invariant system
 - A system is time-invariant if a time shift in the input signal causes an identical time shift in the output signal

$$\begin{array}{c|c} x(t) \\ \hline \\ System \end{array} \begin{array}{c} y(t) \\ \hline \\ System \end{array} \begin{array}{c} x(t-t_0) \\ \hline \\ System \end{array} \begin{array}{c} y(t-t_0) \\ \hline \\ System \end{array} \end{array}$$

- Linear time-invariant (LTI) system
 - A system is both linear and time-invariant.



DETERMINISTIC: SYSTEM

• Impulse response of LTI system

- Def: the output (response) of a system when the input is a unit impulse function (delta function). Usually denoted as h(t)

$$x(t) = \delta(t)$$

$$LTI$$

$$y(t) = h(t)$$

• Response of LTI system to arbitrary input

$$x(t)$$
 $y(t) = \int_{-\infty}^{+\infty} x(\tau)h(t-\tau)d\tau$

Convolution

$$y(t) = x(t) \otimes h(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$$

- Example: evaluate the convolution
$$x(t) \otimes \delta(t - t_0)$$



DETERMINISTIC: SYSTEM

• Example

- A system has impulse response $h(t) = \exp(-at)u(t)$. If the input is $x(t) = \exp(-bt)u(t)$, find the output.



• Fourier transform

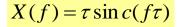
$$X(f) = \int_{-\infty}^{+\infty} x(t) e^{-j2\pi ft} dt$$

- Frequency domain representation of signal.
- Inverse Fourier transform

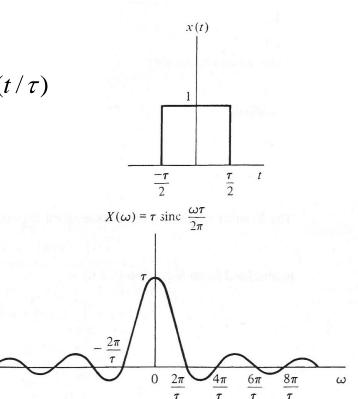
$$x(t) = \int_{-\infty}^{+\infty} X(f) e^{j2\pi f t} df$$

• Example:

- Find the Fourier transform of $x(t) = rect(t / \tau)$







• Selected properties

- Linearity
 - If $x_1(t) \Leftrightarrow X_1(f)$ $x_2(t) \Leftrightarrow X_2(f)$
 - Then $ax_1(t) + bx_2(t) \Leftrightarrow aX_1(f) + bX_2(f)$
- Time shift
 - If $x(t) \Leftrightarrow X(f)$
 - Then $x(t-t_0) \Leftrightarrow X(f) \exp[-j2\pi f t_0]$
- Duality

$$g(t) \Leftrightarrow G(f)$$

- If $g(t) \Leftrightarrow G(f)$ • Then $G(t) \Leftrightarrow g(-f)$
- Convolution
 - If $x(t) \Leftrightarrow X(f) \qquad h(t) \Leftrightarrow H(f)$
 - Then
- $x(t) \otimes h(t) \Leftrightarrow X(f)H(f)$





• Examples

- Find the Fourier transform of $x(t) = \delta(t)$

- Find the Fourier transform of
$$x(t) = \delta(t - t_0)$$

- Find the Fourier transform of $x(t) = e^{-j2\pi at}$

- Find the Fourier transform of $x(t) = A\cos(2\pi f_0 t)$



• Fourier series

- For any periodic signal with fundamental period *T*, it can be decomposed as the sum of a set of complex exponential signals as

$$x(t) = \sum_{n=-\infty}^{+\infty} c_n \exp\left[j2\pi \frac{n}{T}t\right]$$

• Fourier series coefficients:
$$c_n, n = 0, \pm 1, \pm 2, \cdots$$

$$c_n = \frac{1}{T} \int_{\langle T \rangle} x(t) \exp\left[-j2\pi \frac{n}{T}t\right] dt$$

- Fourier transform of periodic signal (perform Fourier transform on both sides of Fourier series) $+\infty$

$$X(f) = \sum_{n=-\infty}^{+\infty} c_n \delta(f - \frac{n}{T})$$

- Parsaval's theorem
 - Energy signal:
 - Power signal:

$$E = \int_{-\infty}^{+\infty} x^2(t) dt = \int_{-\infty}^{+\infty} X^2(f) df$$

$$P = \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{+T/2} x^2(t) dt = \sum_{n = -\infty}^{+\infty} c_n^2$$



DETERMINISTIC: ENERGY SPECTRAL DENSITY

- Energy spectral density (ESD)
 - The distribution of the signal's energy in frequency domain.
 - The "density" of energy. Unit: Joul/Hz
 - E.g. 1: If the ESD of signal x(t) is $\Psi_x(f)$, then the energy in frequency range $(f, f + \Delta f)$ is:
 - E.g. 2: the energy in frequency range (f_1, f_2) is:
 - Def: If $x(t) \Leftrightarrow X(f)$, then the ESD of energy signal is

 $\Psi_x(f) = |X(f)|^2$

• Why?



DETERMINISTIC: POWER SPECTRAL DENSITY

• Power spectral density (PSD)

- The distribution of signals power in frequency domain
 - The density of power (unit: watt/Hz)
- PSD of power signal is the

$$\Psi_x(f) = \sum_{n=-\infty}^{+\infty} |c_n|^2 \,\delta(f - nf_0)$$

• c_n : Fourier coefficient

•
$$f_0 = 1/T_0$$

- E.g. Find the PSD and power of
$$x(t) = A\cos(2\pi f_0 t)$$



OUTLINE

• Deterministic signals

- Random Signals (Ch. 1.5)
- Signal transmission through linear system, bandwidth



• Random variable (RV):

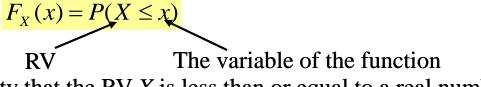
- Random variable: *X*(*A*) represents the functional relationship between a random event *A* and a number *X*.
- Example:
 - Random event A: toss coin;
 - Mapping between coin toss and number:
 - coin head \rightarrow X = 0; coin tail \rightarrow X = 1.

• Discrete RV, probability mass function (PMF)

- Example:
 - An urn has 2 black balls, 5 white balls, and 3 red balls, pick one ball out of urn
 - Random event A: black ball, white ball, red ball
 - RV: *X*: black ball \rightarrow X = 0; white ball \rightarrow X = 1; red ball \rightarrow X = 2.
 - PMF:
- P(X = 0) =P(X = 1) =P(X = 2) =



- Cumulative Distribution Function (CDF)
 - The CDF of a random variable X is given by



- The probability that the RV *X* is less than or equal to a real number *x*.
- Some properties:

$$F_X(-\infty) = 0 \qquad \qquad F_X(+\infty) = 1 \qquad \qquad 0 \le F_X(x) \le 1$$

$$P(x_1 < X \le x_2) = F_X(x_2) - F_X(x_1)$$

$$x_1 \le x_2 \Longrightarrow F_X(x_1) \le F_X(x_2)$$

- Example:
 - The CDF of the RV in the previous example

Discrete RV can be characterized by PMF, CDF



- **Probability Density Function (pdf)** $p_{X}(x) = \frac{dF_{X}(x)}{dx}$
 - The "density" of probability.
 - E.g. the probability that the RV $X \in [x, x + \Delta x]$:
 - The probability that the RV $X \in [x_1, x_2]$:
 - Properties of pdf

 $p_x(x) \ge 0$

$$\int_{-\infty}^{+\infty} p_X(x) dx = 1$$

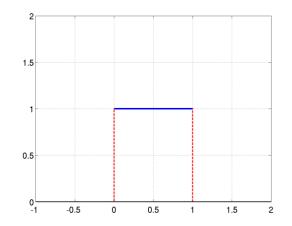


• Continuous RV

- The RV can take continuous values.
- Continuous RV can be characterized by its pdf or CDF.
- Uniform distribution
 - pdf

$$p_x(x) = \frac{1}{b-a}, a \le x \le b$$

The RV X has equal probability to be any value in the range of [a,b]





- Mean (Ensemble Average, 1st moment, expected value)
 - The mean value of a random variable is defined by

$$m_X = E(X) = \int_{-\infty}^{+\infty} x p_X(x) dx \qquad m_X = E(X) = \sum x_k P(X = x_k)$$

- Example:
 - The exponential distribution has pdf

$$p_X(x) = \lambda \exp(-\lambda x), x \ge 0, \lambda > 0$$

- Find its mean value.



• The n-th moment of a RV is defined as

$$E(X^n) = \int_{-\infty}^{+\infty} x^n p_X(x) dx$$

• The n-th central moment of a RV is defined as

$$E\left[(X-m_X)^n\right] = \int_{-\infty}^{+\infty} (x-m_X)^n p_X(x) dx$$

- Variance (average power of a zero-mean random signal)
 - Second central moment. $\sigma_X^2 = E[(X m_X)^2] = E[X^2] m_X^2$

 σ_{x}

– Standard deviation (root mean square value, rms):

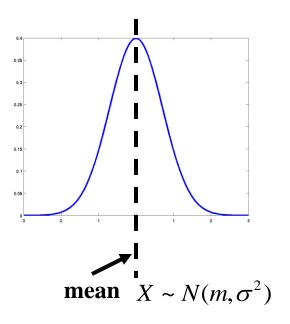


• Gaussian distribution (Normal distribution)

– A random variable is Gaussian distributed if the pd

$$p_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(x-m)^2}{2\sigma^2}\right]$$

- Gaussian pdf is fully characterized by its mean m and variance σ^2
- Y = aX + b is still Gaussian
- Example: prove the mean of Gaussian RV is *m*







• Joint distribution

- Two RVs X, Y, the joint CDF is defined as

$$F_{X,Y}(x, y) = P(X \le x, Y \le y)$$

– Example

X	Y	Prob.
0	0	0.2
0	1	0.2
1	0	0.5
1	1	0.1

- joint PMF: P(X = 0 & Y = 0) =
- marginal PMF: P(X = 0) =
- marginal PMF: P(Y=1) =
- conditional PMF: P(X=0|Y=1) =

(if we already know that Y = 1, what is the probability that X = 0?)



• Independent RVs

- $F_{X,Y}(x, y) = F_X(x)F_Y(y)$ $\leftarrow \rightarrow X$ and Y are independent.

- Independence: there is no relationship between the two RVs.

• Joint pdf

$$p_{X,Y}(x, y) = \frac{\partial^2 F_{XY}(x, y)}{\partial x \partial y}$$

• Marginal pdf

$$p_X(x) = \int_{-\infty}^{+\infty} p_{XY}(x, y) dy$$

$$- p_{X,Y}(x,y) = p_X(x)p_Y(y)$$

Conditional pdf

$$p_{X|Y}(x \mid y) = \frac{p_{XY}(x, y)}{p_Y(y)}$$

$$p_Y(y) = \int_{-\infty}^{+\infty} p_{XY}(x, y) dx$$

$$\bigstar \rightarrow X and Y are independent$$

$$p_{Y|X}(y \mid x) = \frac{p_{XY}(x, y)}{p_X(x)}$$



• Example

- Find the marginal pdf and conditional pdf of

 $p_{X,Y}(x, y) = e^{-x-y}, x \ge 0, y \ge 0$

- Are they independent?



Correlation and covariance

- The correlation between two RVs *X* and *Y*:

$$corr(X,Y) = E[XY] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} xyp_{X,Y}(x,y)dxdy$$

- The covariance between two RVs *X* and *Y*:

$$\operatorname{cov}(X,Y) = E[(X - m_X)(Y - m_Y)] = E[XY] - m_X m_Y$$

• Uncorrelated

- Two RVs X, Y are uncorrelated if

$$\frac{E[XY]}{E[X]} = E[X]E[Y]$$

- If two RVs are uncorrelated, what is their covariance?

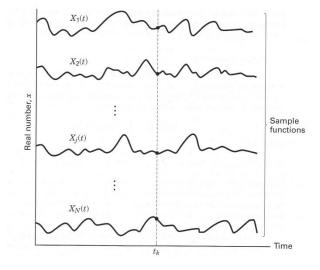
- If two RVs are independent, then they are uncorrelated. (Why?)
 - But not the other way around!!!



RANDOM SIGNAL: RANDOM PROCESS

Random process

- A random process can be viewed as a RV changes w.r.t. time:
 - A function of two variables: *X*(*A*, *t*)
- Sample function: $X_k(t) = X(A_k, t)$
 - Each sample function corresponds to one of the random events.
 - For a specific event A_k , we have a single sample function $X_k(t)$.
 - The collection of all sample functions is called ensemble.
- Random variable: $X(t_k) = X(A, t_k)$
 - For a specific time t_k , we have a RV $X(t_k)$
 - Random process is a collection of RVs.





RANDOM SIGNAL: RANDOM PROCESS

• Mean (ensemble average)

 $m_X(t_k) = E[X(t_k)]$

- The mean is a function of time!

Autocorrelation function

 $R_X(t_1, t_2) = E[X(t_1)X(t_2)]$

- The correlation of two RVs.
- Autocorrelation function is a function of two variables t_1, t_2
- Stationary (strict)
 - A random process is stationary in the strict sense if none of its properties is affected by a shift in time.
- Wide-sense stationary (WSS)
 - A random process is WSS if its mean and autocorrelation function do not vary with a shift in the time.
 - Mean is independent of time:
 - Autocorrelation depends only on time difference:

$$m_X(t_k) = m_X$$

$$R_X(t_1, t_2) = R_X(t_1 - t_2)$$

$$= R_X(\tau)$$



RANDOM SIGNAL: RANDOM PROCESS

• Example:

Consider a stationary sequence of independent binary bits. Each bit has equal probability of being or -1 or 1. The bit period is T.

- Find the mean of the random process.
- Find the average power of the random process.



RANDOM SIGNAL: POWER SPECTRAL DENSITY

• Power spectral density (PSD)

- The distribution of the signal's power in the frequency domain.
 - The "density" of power in the frequency domain (unit: watt/Hz).
- It allows the evaluation of signal power in a certain frequency range.
 - The power in frequency range $[f, f + \Delta f]$:
 - The power in frequency range $[f_1, f_2]$:
- PSD of a WSS random process is the Fourier transform of its autocorrelation function

 $G_X(f) = F[R_X(\tau)]$



RANDOM SIGNAL: NOISE

• Noise

- Unwanted electrical signals that are always present in electrical system.
 - Man-made noise: spark-plug ignition noise, switching transients, other radiating electromagnetic signal.
 - Natural noise: thermal noise, elements of atmosphere, etc.

• Thermal noise:

- Caused by thermal motion of electrons in all electronic components: resistors, diodes, transistors, wires, ...
- Become worse with the increase of temperature.
- Thermal noise is a random process X(A, t)



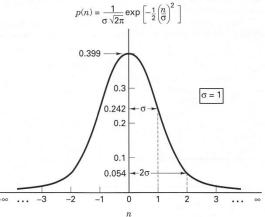
RANDOM SIGNAL: NOISE

- Statistical properties of thermal noise
 - At a specific time t_k , $X(A, t_k)$ is zero-mean Gaussian distributed
 - Gaussian noise

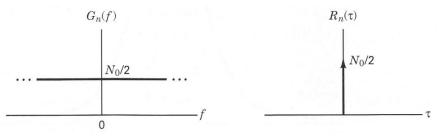
$$p_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{1}{2}\left(\frac{x}{\sigma}\right)^2\right]$$

- Its power spectral density is the same for all frequencies.
 - White noise
 - PSD

$$G_X(f) = \frac{N_0}{2}$$



- Autocorrelation function: $R_{x}(\tau) =$
 - Any two different noise samples are uncorrelated.



Additive White Gaussian Noise (AWGN)



OUTLINE

• Deterministic signals

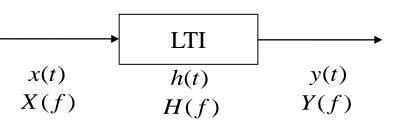
• Random Signals

• Signal transmission through linear system, bandwidth (Ch. 1.6, 1.7)



TRANSMISSION

• LTI system



• Frequency transfer function (frequency response)

$$H(f) = \frac{Y(f)}{X(f)} = F[h(t)]$$

- In general, H(f) is complex

$$H(f) = H(f) | e^{j\theta(f)}$$

• Magnitude response:

$$|H(f)| = \sqrt{\text{Re}^2 \{H(f)\} + \text{Im}^2 \{H(f)\}}$$

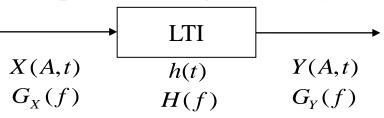
• Phase response:

$$\theta(f) = \arctan \frac{\operatorname{Im}\{H(f)\}}{\operatorname{Re}\{H(f)\}}$$



TRANSMISSION

Random process passes through linear system



- If the input is a random process X(A, t), then the output is a random process Y(A, t).
- Generally speaking, *Y* and *X* follow different distributions
 - However, if *X* is Gaussian distributed, *Y* is still Gaussian!
 - Linear combination of Gaussian is still Gaussian.
- The PSD of *X* and *Y* are related by the following equation

 $G_{Y}(f) = G_{X}(f) |H(f)|^{2}$

If the input is white Gaussian random process, then the output is colored Gaussian with PSD determined by *H*(*f*) → this can be used to generate colored Gaussian random process.



TRANSMISSION: IDEAL TRANSMISSION

- Ideal transmission (distortionless transmission)
 - The output has some delay compared to the input
 - The output has a different amplitude compared to input
 - It must have the same shape as the input: no distortion.

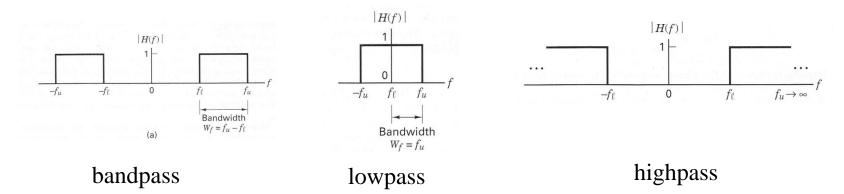
 $y(t) = Kx(t - t_0)$

- Frequency domain system equation:
- Transfer function:
 - Amplitude response:
 - Phase response:



TRANSMISSION: IDEAL TRANSMISSION

• Ideal filters



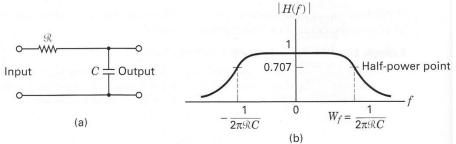
- Example
 - Pass a white noise with PSD $G_x(f) = \frac{N_0}{2}$ through an ideal low pass filter with bandwidth f_u . Find the autocorrelation function at the output of the filter.

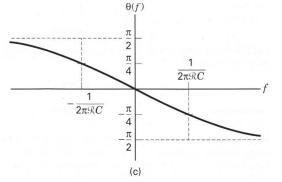


TRANSMISSION: RELIAZABLE TRANSMISSION

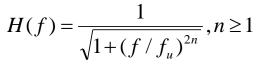
- Example:
 - RC filter

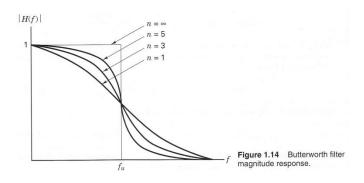
$$H(f) = \frac{1}{1 + j2\pi fRC}$$





– Butterworth filter







TRANSMISSION: BANDWIDTH

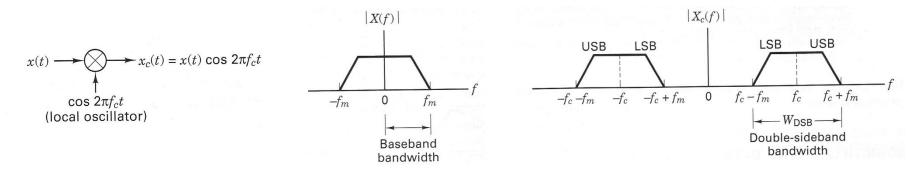
• Baseband v.s. Bandpass

- A baseband signal can be shifted to a higher frequency by multiplying it with a carrier wave $\cos 2\pi f_c t$

 $x_c(t) = x(t)\cos 2\pi f_c t$

- In the frequency domain

$$X_{c}(f) = \frac{1}{2} \left[X(f - f_{c}) + X(f + f_{c}) \right]$$



DSB: Double side band, USB: upper side band, LSB: lower side band

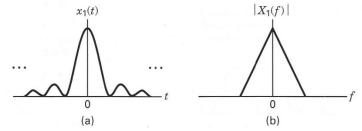
Bandpass bandwidth is twice of baseband bandwidth.



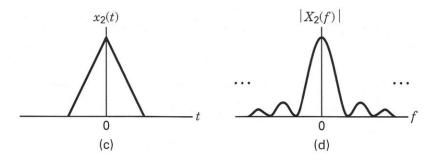
TRANSMISSION: BANDWIDTH DILEMMA

• Dilemma

- Strictly band limited signal imply infinite duration



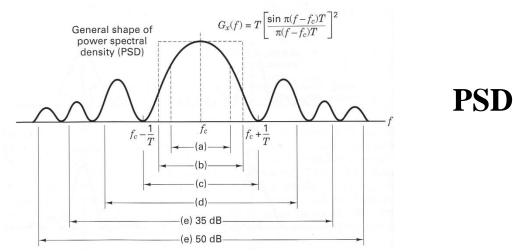
- Duration limited signal has infinite bandwidth



A signal cannot be limited in both time domain and frequency domain.
duration limited signal is realizable → realizable signal is unlimited in frequency domain.



TRANSMISSION: BANDWIDTH DEFINITION



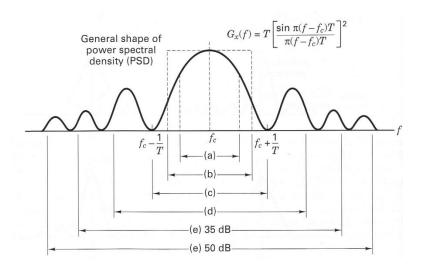
- (a) Half-power bandwidth:
 - The interval between which that G(f) has dropped to half (3 dB) of its peak value. $G(f_{3dB})/G(f_c) = 1/2$
- (b) Equivalent rectangular bandwidth
 - The bandwidth of an equivalent rectangular filter with magnitude the same as the peak of G(f) and has the same total power of G(f)

 $W = P/G(f_c)$

- (c) Null-to-null bandwidth
 - The width of the main spectral lobe.



TRANSMISSION: BANDWIDTH DEFINITION



- (d) Fractional power containment bandwidth (FCC definition)
 - The occupied bandwidth is the band that leaves exactly 0.5% of the signal power above the upper band limit and exactly 0.5% of the signal power below the lower band limit. Thus 99% of the signal power is inside the occupied band.
- (e) bounded power spectral density
 - Everywhere outside the specified band, G(f) must have fallen at least to a specified value (e.g. 35 dB) below its peak value.
- (f) absolute bandwidth:
 - The interval between frequencies, outside of which the PSD is zero.

